

IPL

INDUCTION
and the PROBLEM of LEARNING

Induction and the problem of learning.

Gen. outline of presentation, and abstract, emphasizing positive results.

1. Outline normal learning and induction process
- a) selection of ~~cases~~ classes
- b) case counting
- c) combining data of ~~the~~ case counting (B.G.)
- d) modifications on case selection.

1) First describe ~~the particular learning problem~~ the particular learning problem, telling about i.p. (?), describe just what is presented to the machine, and just what is expected of it.

2) Show that what the machine must do, is a prediction problem, and is a special case of the d.d.t.s. Also mention that most, if not all learning ^{problems} are expressible as a t.s. prediction.

Mention that approach to mechanics of machine behavior will be attempt at recreating in it, what I believe to be close to my own mental processes in solving the problem.

3) Give a few cases of d.d.t.s prediction, using u.g.m.s.

4) " cases in which g.p.s must be formed, because of small sample size (say, usually zero sample size).

5) Dwell on necessity of forming good g.p.s. — how ad-hock g.p.s. usually result in poor prediction.

6) How the B.G. problem arises. Note that I will

~~not go into~~ B.G. — that I think a very poor approx. soln. is adequate.

Since one is, in learning problems g.n. a history of correct ^{stim-} responses, and is g.n. a new stim. and

asked for a response. Another learning problem:

g.n. pairs of s. r.'s with their g's, ^{g.n. a new} s; to devise a R of maximum ^{expected} G.

7) Some ways in which g.p.s are formed. Some g.p. parameters (U, sample size, freq. ~~f~~), U may have several components — depending on sample size available). Factoring of g.p.s into atpst, strsts

8) Why U is imp. and ~~how~~ ^{some ways in which} it may be evaluated

9) The specific problem; how =, ~, β , βT , + (with carry line, then without carry line in linear notation) is accomplished.

10) Describe present difficulties, future expectations.

Rewrite this outline, changing the ordering somewhat.

1) should come later ~~to~~ 9)

1. Describe some learning problems, then try to generalize to characteristics of all ^{or many} learning problems.

some cases

① Simple rote learning: e.g. a) spelling b) Arithmetic tables.

② Problems involving somewhat more complex abstractions: ^{Multisub. - depending on how taught.} or trigonometric

a) Arithmetic addition (without carry line). b) algebraic simplifications

c) soln. of alg. eqns.

d) ~~literal~~ literal integration. e) interpolation, extrapolation of functions. f) Proofs [involving the idea of searching]

$\frac{A}{B}$

Trouble is, it is not clear from the above that the machine would ever solve any really difficult, or interesting problems. ~~How~~ After some of these mathematical probs. it might be possible to get the machine to answer questions in English. Note that the math T.M. was undertaken mainly as a method of studying the abstraction process, and not as a goal in itself

The point is, most learning problems can be presented as extrapolation, or induction problems.

2. How these are examples of prediction: that a time series is ~~what~~ ^{an instance} of the more general kind of prediction problem. A t.s. may be continuous or discrete, or a mixture. The d.d.t.s. is of most interest, and is most difficult.

3. The ^{and against} ~~against~~ as used in d.d.t.s. prediction. The problem of specificity v.s. sample size.

4. How ~~good~~ gps (gp \equiv ngust) are nec. to give sample size > 0 .

5. How good gps. give good prediction - how ad hoc gps. are O.K., but of little value in prediction.

6. How B.G. ~~arises~~ arises ("combination problem") - that it probably isn't an imp. problem, in the sense that a poor soln. is probably O.K.

7. Some ways that gps are formed - factoring them into str, strsts, utpsts. Some ~~dimensional~~ examples of str, utpsts. Some ~~gp~~ gp params: U, samp. size, freq., Δp .

8. Why U is imp: How it corresponds to the elevation of a gp. to a "word".

9. Describe ~~the~~ specific problem of Math T.M. = $\sim, \beta \leq, \beta \pi, +$ (with carry line)

9. Show some of the gps, strs, utpsts that have been useful.

10. Give some future problems: e.g. mult., literal alg., solving equs., differentiating, Integration, iterative (numerical) solu. of diff. equs., proofs, etc.

11. The problem of getting T.M. to understand English, and how "concept formation" may be induced by R.W. continuous problems.

11. Index.

1. Many learning problems can be looked upon as problems in induction, or extrapolation. One is given several solved examples similar to the problem of interest, and then one is expected to solve it. I believe that in general, the problem of induction, contains most of the significant, difficult problems of learning, and much can be learned about learning by studying the induction process. An aspect of importance in many learning processes, that does not seem to appear in ~~many~~ most induction processes, is the concept of the "sub-goal". I believe, however, that the concepts useful in solving induction problems will also be adequate in the suggesting of ^{trial} sub-goals ~~in~~, in certain learning problems.

* Some caricature of learning problems with sub-goals, and how abs. process would be helpful. see (4.03)

2. Some examples of ~~some~~ learning are as follows.

a) simple rote learning, as spelling or arithmetic tables. In the former, a spoken word is presented along with its graphic representation. The learner must then reproduce the graphic representation, after hearing the spoken word. Similarly with arithmetic table learning as $3+4=7$.

* The above example is very poor. The true learning process in spelling e.g. is much more complex, and has a longer history of cases than the single case given. Similarly in Arithmetic ~~table~~ table learning.

b) A very general kind of arithmetic learning problem is described on page

c) b) Trigonometric identity proving and Theorem proving. These involve search processes in which no specific

exhaustive routine is taught. The general technique is obtained by the student thru induction.

-03 * Also poor example, since they involve sub-goals (usually) and we may not want to deal with such problems. Actually, ~~the~~ restriction of induction to problems without sub-goals, is a bit artificial. I must investigate ~~the~~ ~~process~~ & process of sub-goal formation in these induction problems ~~see above~~ →

d c) ~~Why word and language~~

Initial word and language learning by a child. The child notes that certain sound sequences are associated with the presence of certain situations. The process by which the child is able to "name" a situation (eg. presence of mother or father → "Mama", "Dada") is a rather complex induction ~~problem~~ ^{trying to} problem. The conclusion, by the child, that ^{trying to} imitating his parents' sounds in these situations is desirable, is an induction process.

* The above paragraph is a rather questionable way of looking at the phenomenon discussed. ^{at least, many people will question it.} Imitation may be a built-in response, requiring no reinforcement. However, even if it is built-in, this simply gives the child's conclusions by arip., and so he must still use induction.

* ~~process~~ ^{process} The formation of sub-goals in the soln. of "search" problems, is a technique T.M. can discover for himself, or it can be taught to him by a ~~eng.~~ seq. designed for such a discovery. However, the exact abstractions made in this inductive process, and their plausibility — (i.e. how readily they stem from other abss., must be looked into. The formation of sub-goals may ~~involve~~ involve an induction technique of a significantly different ("hyer") type than other previous inductions. I think we may, however, be able to take this in our stride.

e d) Learning problem involving maximizing reward received for response behavior. The organism is given a stimulus, S_i , and it presents a response, R_j to the environment. The environment presents a reward G_{ij} to the organism. After many S_i, R_j ~~pairs~~'s are tried, and G_{ij} 's received, the organism tries to find R_j 's such that the G_{ij} 's they will receive are maximal. The pure induction problem involves predicting the expected ~~value of G_{ij}~~ ~~from a S_i, R_j pair.~~ value of G_{ij} from a S_i, R_j pair.

* ~~This~~ This problem is more complex than the simple induction problem. The organism is always faced with the occasional choice of doing an experimental ~~try~~ R_j to gain information, rather than to try to get an immediate large G_{ij} . Also, as the problem has been formulated above, even if one could predict the expected G_{ij} from any S_i, R_j pair, ~~one still has~~ one still has the search problem (of the 2nd kind), that ~~wants~~ for fixed S_i , we must find a R_j such that G_{ij} is maximal. In a well-designed machine, the soln. to the problem may not proceed in the step-wise manner as above, i.e. finding ^{a formula for} an expected G_{ij} from an arbitrary S_i, R_j pair, then optimizing R_j for fixed S_i . The machine may proceed directly to find ~~optimum~~ a method to obtain ~~the~~ optimum R_j , given S_i .

In such a case, it is not clear that we have a simple induction problem.

We can, however, separate the problem as given, into an induction-problem, plus a search problem.

f e) The Problem of a scientist. One of the problems of a scientist, is to predict what will follow from arbitrary initial conditions. He ~~does this~~ attempts to do this by observing many cases and drawing inductive conclusions. He may or may

~~2. The above examples are all cases of prediction.~~

~~As such, they~~

not draw up a formal "law of nature" to aid in the extrapolation. In either case, the process may be looked upon as either induction or learning.

imagine \rightarrow

2. The above ~~cases~~ ^{involve} examples ~~but~~ all ~~involve~~ prediction. As such, they ~~can be looked upon as examples of time series~~ all bear a strong structural resemblance to time series. We shall

* ~~The formal resemblance between time series' and other prediction problems should be clarified. i.e. A time series, ^{problem} usually involves prediction of the next element, ~~when~~ following a long known sequence. In many prediction problems, however, ~~the problem is to predict~~ one is given many members of the series, and then one is given a member that is incomplete, and asked to complete it. e.g. one's Given many correct, completed arithmetic addition problems, then one is given $1 + 7 =$. ^{The problem is} to complete the ~~then~~ equation.~~

including ~~and~~ ^{Actually,} ~~but~~ all of the induction problems, ~~and~~ time series' are special cases of 2.

following: Given a large object ~~which~~ that may be composed of many related or unrelated parts: Suppose that part of this object is unknown to you - ~~the~~ the problem is to predict just what it is.

At any rate the concepts ~~problem~~ useful in time series prediction are also useful in the general induction problem.

\rightarrow discuss time series' in some detail, since ~~that~~ ~~concepts used will be useful in the~~ ~~easy~~ to find simply describable examples, that ~~have many~~ ~~do~~ exhibit properties that are very useful ~~in~~ in discussing the general induction problem.

Time series are of several types. One method of classification is on the basis of whether time

a) ~~Continuous in time, with continuous variation in parameters of members.~~

b) ~~Discrete~~

is a discrete or continuous variable, and another depends on whether the elements of the time series have discrete or continuous values of the parameters that describe them.

Examples:

a) Discrete time, discrete elements: Printed English, Morse code signals.

b) Discrete time, continuous elements: Peak daily temperature readings.

c) Continuous time, discrete elements: stock market readings

d) Continuous time, continuous elements: most sound or electrical signals; noise.

The type of series we will study most extensively is type a): discrete time, discrete elements. The limitations of this choice will be dealt with later. It is believed that the

* This limitation is in the Real world to - language conversion problem, and the evolution of spacial concepts "in an organism.

< > doubly discrete time series is by far, most difficult to deal with, has had little work done on it, and is most important, in terms of idea evolution the life that it throws on other problem indicates induction problems.

3. Let us consider the problem of predicting printed English. The concept that I would like to use is that of the "n-gram" / ^{as used by Shannon in PEPE.} An n-gram is an ^{ordered} sequence of n elements. Elements may be letters, small or large, punctuation and small and large spaces. In printed English we may have on the order of 60 different possible "elements".

Suppose we have a long English text, ~~marked~~ that is abruptly truncated and we want to predict the next element. For a rough approximation, we can make a frequency count of each of the 60 elements, and make a set of probabilistic predictions ~~directly~~ based ~~on~~ directly upon them.

For a more ~~more~~ accurate prediction, we may note the ~~last~~ element with which the truncated text ends, and make frequency counts for all digrams that begin with that ~~last~~ element. We may on this basis, ~~more~~ usually make a more accurate prediction.

In a similar way, we may look at the last $n-1$ elements of the text, and ~~count~~ make frequency counts of n -grams that begin with those $n-1$ elements.

As n increases, we might expect some increase in prediction accuracy, providing the text was long enough to give a large ~~enough~~ of ~~statistical~~ sample of these n -grams.

* ~~Shannon has shown, however, that prediction accuracy increases ^{only very} slowly for $n > \text{say, } 100$~~

→ Unfortunately, however, since our text is of finite length, n cannot be very large, or else the advantages of good predictions thru large n , will be overbalanced by the ~~small sample~~ low accuracy due to small sample size.

insert →

Let us examine this situation more carefully and try to generalize. In any prediction problem we are confronted by a set of conditions ~~that~~ from which we try to make a prediction. Ideally, this set of conditions ^{will} have occurred many times before, and accurate probability estimates can be made. More often, however, the set of conditions ~~is~~ has never before occurred in exactly the same way. In such a case, we try to classify the event to be predicted, within a larger class of events, of which we have a sufficiently large sample, so that reliable probability estimates may be made.

insert: α , pages.

~~the text~~ Suppose our text ended with the ~~elements~~ elements $\dots e_4 e_7 e_2 e_3$, ~~with that the rest~~

We may represent the rest of the previous text by A_r , (which contains r elements), so the entire truncated text becomes $A_r e_4 e_7 e_2 e_3$. We wanted to know

~~When we made frequency counts on the elements e_2, e_3, \dots, e_7 .~~

The relative probability of the various sequences $A_r e_4 e_7 e_2 e_3 e_i$, for all 60 values of i .

When we made our predictions on frequency counts of the e_i elements only, we essentially inserted the sequence $A_r e_4 e_7 e_2 e_3 e_i$

in the set of all $r+5$ -grams that end in e_i . In a similar way, by ^{when we made our predictions} making frequency counts on the ~~trigram~~ tetragram $e_7 e_2 e_3 e_i$, we inserted our sequences in the set of all $r+5$ -grams that end in $e_7 e_2 e_3 e_i$.

It should be noted that usually there are fewer $r+5$ -grams that end in $e_7 e_2 e_3 e_i$ than there are $r+5$ -grams that end in e_i .

* Actually, we shouldn't let $A_r e_4 e_7 e_2 e_3$ be the entire truncated text. This tends to make sample sizes too small. ~~Better~~ Better let $r=0$ or some small number. — No, on 2nd thought, this use of $A_r e_4 \dots e_3$ is O.K. — perhaps it should be added, for clarity, that one knows that the ^{truncated} text is at least $2(r+5)$ elements long, but one only knows the last $r+5$ elements.

Loosely speaking, we try to classify the event in a class as "close" to it as possible, yet which has ~~larger~~ happened sufficiently frequently in the past so as to give it reliable statistics. In general, we must compromise between an extremely "close" class with few members, and a desire for a class that has occurred many times in the past, that often has many members, and is not ~~too~~ ^{as} closely related to the event of interest.

The problem of ~~assigning~~ ^{assigning} events to classes, ~~rather~~ and ~~inventing~~ ^{inventing} useful classes, will be the main problems to which we will direct our selves ~~in this presentation~~. In addition, we shall concern ourselves with the assignment of parameters to these classes, so that they might be used in prediction.

As might be suspected, the ideal solution to the ^{problem of} classification of ~~an event~~ an event, lies in its assignment to all classes that contain it. The prediction problem involved is rather complex, however, and usually only the roughest approximations to the ideal solution will be attempted.

4. The devising of ~~useful~~ suitable classes is of most importance in prediction, and prediction ~~effectiveness~~ effectiveness will depend upon how well one has chosen them. For instance if one is accosted by a grizzly bear, one's prediction of ~~its~~ its future behavior would be best, if one categorized it ~~as an event with~~ ^{as} grizzly bears, rather than ~~with~~ ^{as} mammals.

The confidence that one has in a classification will depend upon how the class was constructed, how many times events have been observed in the class, how many members there are in the class, ~~as well~~ and ~~several~~ other factors.

Usually one tries to chose a class ~~containing~~ containing as few members as possible, yet ~~has~~ ^{has} ~~never~~ ^{never} occurred reasonably frequently yet whose members have occurred with reasonable frequency. Also, it is usually expedient that the description of the class ~~is~~ ^{is} ~~not~~ ^{not} ~~too~~ ^{too} ~~long~~ ^{long} ~~and~~ ^{and} ~~that~~ ^{that} ~~has~~ ^{has} ~~been~~ ^{been}

~~Ad-hoc~~

be "simple." This "simplicity" will be with respect to the definition of the class within a language that has proved useful in the past.

~~the~~ simplicity of class description is formally equivalent to ~~the~~ a "scientific methodology" rule of thumb called "Occam's Razor". These concepts will ^{later} be used as a guide ~~to~~ to the more ~~exact~~ ~~for~~ precise formulation of class prediction parameters.

Another example of a very poor kind of class, is the ad-hoc class..... Suppose we want to predict the next ~~to~~ element of a sequence ~~which~~ that terminates in a_1, a_3, a_1, a_2 , and there are only 3 different kinds of elements; a_1, a_2 and a_3 . What we want, is the relative frequencies of the 3 ~~ad-hoc~~ sequences

$$A_1 \equiv a_1, a_3, a_1, a_2, a_1$$

$$A_2 \equiv a_1, a_3, a_1, a_2, a_2$$

and ~~A3~~ $A_3 \equiv a_1, a_3, a_1, a_2, a_3$.

If none of these sequences have occurred sufficiently frequently to give a good probability estimate, we must express each of them as members of a ~~single~~ ~~set~~ set of sequences, such that the ~~set~~ ~~of~~ ~~members~~ ~~have~~ ~~sufficiently~~ ~~frequently~~ ~~total~~ ~~frequency~~ of occurrence of members of each of these sets is sufficiently high. A possible set would, as was suggested before, be the placing of a_1, a_3, a_1, a_2, a_1 in the set of all pentagrams that end in a_1 .

Suppose, however, that we place a_1, a_3, a_1, a_2, a_1 in the set of pentagrams whose members are, ad-hoc, defined to be a_1, a_3, a_1, a_2, a_1 ~~and~~ and ~~a_1, a_2, a_1, a_2, a_1~~

Similarly, we can form the class ~~of~~ of members a_1, a_3, a_1, a_2, a_2 and a_3, a_3, a_3, a_3, a_3
the class
and / of members a_1, a_3, a_1, a_2, a_3 and a_1, a_1, a_1, a_1, a_1 .

This "ad-hock" discn. may be an unnoc. digression

Suppose, further, that $a_2 a_2 a_2 a_2 a_2$, $a_3 a_3 a_3 a_3 a_3$ and $a_1 a_1 a_1 a_1 a_1$ are all pentagrams of rather high frequency of occurrence — much higher than A_1 , A_2 or A_3 . Our class frequencies would then be largely governed by the frequencies of the arbitrarily chosen sequences and to very little extent by the frequencies of the sequences A_1 , A_2 and A_3 .

~~The reason this method of prediction would not be used, is that the 3 ad-hock classes would be given~~

Fortunately our final prediction of the probability distribution of the next element, would be determined by the memberships of A_1 , A_2 and A_3 in several classes other than the ad-hock classes. In particular, the classes which were constructed from in "acceptable ways", would be given much more weight in the prediction, than would the arbitrarily constructed ad-hock classes.

~~As a simple example of a set which is constructed in an "acceptable way" is the class or set of all pentagrams that end in $a_1 a_2 a_2 a_1$.~~

Various methods of set construction, and their degree of "acceptability" will be dealt with at some length.

5. A problem of much importance, is that of combining data due to the membership of an event in several different sets.

For example, fighter A has won 80% of his matches, ~~fighter B has won~~ and fighter B has won 70% of his matches.

~~Now~~ Now A is matched against B. What is the best way we can use the available data to determine the probability that A will beat B?

Altho this problem is interesting, difficult, and important, I shall not dwell up it at this point. Although a tentative solution has been obtained, I think that it is very probable that an extremely rough approximation will be sufficient to achieve quite useable results.

6. A parameter ^{of sets} that is of much importance in prediction, is the ~~value~~ "Usefulness" of the set. This parameter ~~describes~~ tells how much more effective prediction is when one uses this set, than it is without the use of that set. In order to evaluate usefulness, it is necessary to evaluate the effectiveness of a prediction run. Any of several methods may be used to do this. Probably the methods devised by J. McCarthy in his "Paying the weatherman" are more than adequate.

Sets with high usefulness values might be that of ^{often used} words or phrases in a language. In the ~~problem~~ problem of combining statistics of events that belong to several different sets, usefulness of a set is an important parameter in determining how much weight it is to get.

7. At this point we will give some examples of important kinds of ~~various~~ prediction sets, and how one may obtain new ones that have a reasonable likelihood of being useful, by suitable operations upon old useful sets. On a more intuitive level, this amounts to combining old ~~scientific~~ scientific concepts and theories to obtain new theories that have a reasonable ~~likelihood~~ ^{a priori} probability of usefulness.

To give these examples, we will investigate a particular induction problem that seems to illustrate them.

~~Under the following~~ The problem consists of presenting the machine with correctly worked examples of arithmetic problems. After the machine has been ~~presented with~~ given many such examples, it will be presented with a problem in which some of the ~~figures~~ ^{digits} are missing, and it will be asked to find the probability distributions for the missing digits. ~~Altho this approach~~ ~~has been applied to arithmetic, for~~ Altho this approach has been applied to arithmetic, for the most part, it is felt that most, if not all, mathematical problems, could be presented to the machine in this form.

The first kind of problem we will present will be equality. The ~~comparison~~^{machine} will be presented with the following set of examples:

= 1001 , = 1010 , = 0110 , = 0001
1001 1010 0110 0001

etc. We present the machine with a series set of examples in which the first line starts with =, and is followed by a random sequence of 4 0's and 1's. The next line contains a duplication of the sequence of 0's and 1's.

We then present the machine with a problem as

= 1101
1[?]01.

We want the machine to reply by giving the probability distributions of 82 various elements that might be in the square marked [?]

A first approximation by the machine would simply give the relative frequencies of the four different possible elements =, 1, 0, =, space. If the examples were presented on a 7 x 10 array, each example would have one equals sign, on the average of 4 0's and 4 1's, and 61 spaces. The relative probabilities as computed from 82's data, would be:

= : $\frac{1}{70}$
0 : $\frac{4}{70}$
1 : $\frac{4}{70}$
space : $\frac{61}{70}$.

We note that in our own thinking about the problem, we would not give such high probability to the space. This is because we have some reason to believe that the 0's, 1's and = are of more interest than the spaces, and are more likely to be the right answer.

If we had asked the machine many

in the past, and had given him the correct answers, questions/ he would, indeed, soon find out that most of the answers were zeros or ones.

We can present this information to the computer machine by making every example have a ? space in it, and then indicate later, to the machine, what the right answer is. For a machine of a deterministic kind, in which we know its internal workings, there is no essential difference between ~~the machine~~

a) Asking the machine a question, letting it guess at the answer, and then telling it ^{the correct} the answer

or b) Giving the machine the correct answer to a question, then telling it what the question was.

For this reason, we will present each example as if it were a question, and we will indicate the correct answer. This can be done by giving our examples in the following form:

= 1001 = 1010 = 0110 = 0001
 1001 , 1010 , 0110 , 0001 ,
etc.

Here we have indicated at what position the question would have been asked, and we have indicated the correct answer.

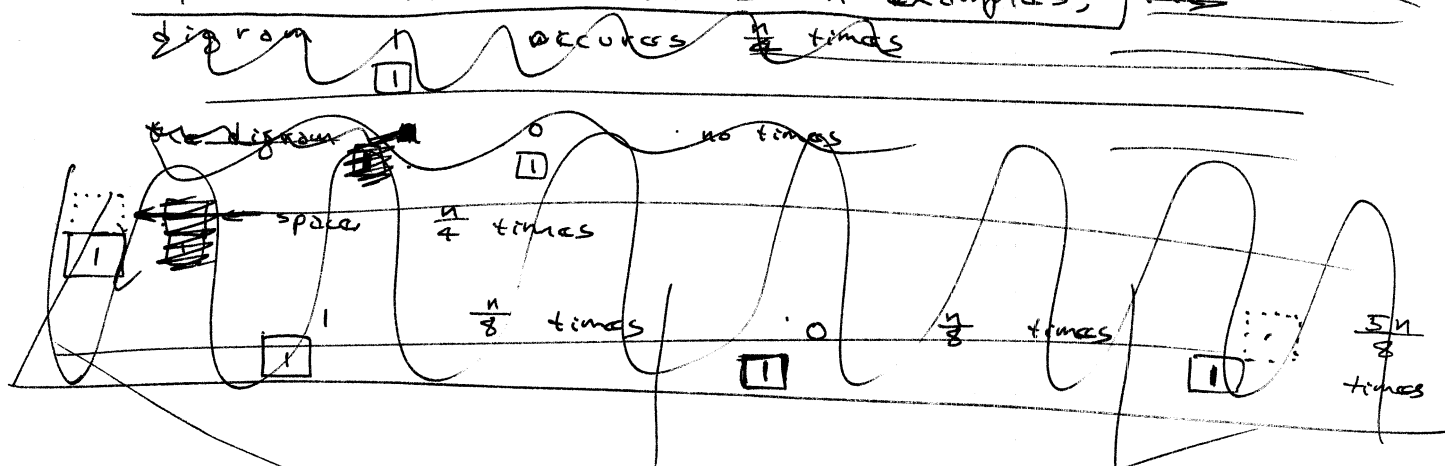
This device is used to direct the machine's attention to the factors of interest. In the real world, ~~this is done by learning from experience~~ one learns that the factors of interest in examinations tend to be the factors that one was asked questions about in previous examinations. The above device is an attempt to simulate this situation. It is felt that it will be possible, later in the life of the machine, to discard this device, and the machine will be able to decide by itself, what factors are likely to be of importance. In such a case, the machine would, on the average, gain more information from an example than at

present. This is because usually there are many squares in an example that would be equally likely candidates for interrogation with respect to probability distribution of digits.

If we do not ~~not~~ put our "interrogation square" around the = sign, the relative element frequencies will be 50% for 0 and 50% for 1.

These ~~probabilities~~ frequencies were obtained in a manner analogous to ~~frequency~~ direct frequency counts of characters in printed English. We shall now employ the analogs of n-grams, as used in Shannon's "Prediction and Entropy of Printed English".

We will ^{first} observe ~~the~~ the frequencies of oriented pairs of digits that include the interrogation square. If we observe n examples,



the following digrams will occur with the noted frequencies:

digram:	1	0	space	1	0	0	1	1	1	1	
no. of times it occurs	$\frac{n}{4}$	0	$\frac{n}{4}$	$\frac{3n}{32}$	$\frac{3n}{32}$	$\frac{5n}{16}$	$\frac{n}{4}$	$\frac{n}{4}$	0	$\frac{n}{4}$	$\frac{3n}{16}$

Suppose we are now given the problem:

$$= 1101$$

$$11?1$$

If we use the digrams 0 and 0

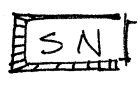
we will arrive at the conclusion that the digit in question is 0, with a probability close to unity. On the other hand, there are many other digrams that might, at first glance, be equally likely to give

Suppose we are now given the problem

$$= \begin{matrix} 1101 \\ 11\boxed{?}1 \end{matrix}$$

We want to know the relative probabilities of
 $A = \left\{ \begin{matrix} 1101 \\ 11\boxed{0}1 \end{matrix} \right\}$ and $B = \left\{ \begin{matrix} 1101 \\ 11\boxed{1}1 \end{matrix} \right\}$

We may classify A is by means of the digram $\boxed{0}$. This digram corresponds to the class of all examples that contain $\boxed{0}$ in them. Similarly, we may classify B with the digram $\boxed{1}$. The first digram would occur $\frac{n}{2}$ times in n examples, the second digram never. The probability obtained for A, would be $\frac{1}{2}$ about unity, for B, about zero.



It might be well to include my reasons for choosing ~~words~~ digrams and objects of hy U, to ~~make~~ construct objects of greater complexity, with "hy" expected U: This would involve explaining why Occam's razor is trivial - how new ideas are always made of "minimal combination" of ~~old words~~ old words. I.E. A theory is "simple" in str. if it uses few "words" in th. old lang. Th. "words" in th. old lang. are upasts that have proved useful.

If we observe n examples, we will note the following approximate digram frequencies, for \boxed{s} denotes a blank space

Digram Configuration	1	0	s	1	0	s	1	0	s
no. of times 0 appeared in interdig. square	0	$\frac{n}{4}$	$\frac{n}{4}$	$\frac{3n}{32}$	$\frac{3n}{32}$	$\frac{5n}{16}$	$\frac{3n}{16}$	$\frac{3n}{16}$	$\frac{n}{8}$
no. of times 1 appeared in interdig. sq.	$\frac{n}{4}$	0	$\frac{n}{4}$	$\frac{3n}{32}$	$\frac{3n}{32}$	$\frac{5n}{16}$	$\frac{3n}{16}$	$\frac{3n}{16}$	$\frac{n}{8}$

Suppose we are now given the problem

$$= \begin{matrix} 1101 \\ 11\boxed{?}1 \end{matrix}$$

